

[MRC102] ROBOT PROGRAMMING

GENERAL INFORMATION

Studies	Master's Degree in ROBOTICS AND CONTROL SYSTEMS		Subject	?
Semester	1	Course	1	Mention / Field of specialisation
Character	COMPULSORY		Language	CASTELLANO/EUSKARA
Plan	2023	Modality	Face-to-face	Total hours
Credits	6	Hours/week	0	60 class hours + 90 non-class hours = 150 total hours

PROFESSORS

ELKOROBARRUTIA LETONA, XABIER
ALONSO NIETO, MARCOS

REQUIRED PREVIOUS KNOWLEDGE

Subjects	Knowledge
(No specific previous subjects required)	Basic programming concepts

LEARNING RESULTS

LEARNING RESULTS	KC	SK	AB	ECTS
M1R211 - [!] <i>Programar un robot para que se obtenga el comportamiento cinemático deseado</i>			x	4,4
M1R223 - [!] <i>Capacidad de trabajar en equipos multidisciplinares y en un entorno multilingüe y de comunicar, tanto de forma oral como escrita, conocimientos, procedimientos, resultados e ideas relacionadas con los temas afines al máster</i>		x		0,4
M1R224 - [!] <i>Capacidad para ejercer su profesión con actitud cooperativa y participativa, y con responsabilidad social</i>		x		0,4
M1R226 - To apply the knowledge acquired and your problem-solving skills in new, little-known or changing environments within broader (or multidisciplinary) contexts related to your area of study		x		0,8
Total:				6

KC: Knowledge or Content / SK: Skills / AB: Abilities

CONTENTS

Industrial Robot Case Study: ABB Robot Studio and IRB 140:

1. Robot Programming Environment
 2. Basic concepts: Targets, work object, paths, …
 3. Programming with RAPID
 4. Interacting with the environment with I/Os
 5. Interacting with the robot through ETHERNET

ROS

1. Introduction to ROS
 2. Publisher/subscriber and client/server models
 3. Development tools
 4. Simulation: RVIZ/Gazebo

LEARNING RESOURCES AND BIBLIOGRAPHY

Learning resources	Bibliography
Moodle Platform Specific Master Software Slides of the subject Labs Topic related web quires	Mastering ROS for Robotics Programming: Best practices and troubleshooting solutions when working with ROS Lentin Joseph & Jonathan Cacace. Packt Publishing, 3rd edition, 2021